## Modern Algebra 1: Midterm 2

## November 11, 2013

- Answer the questions in the space provided.
- There are 5 questions. There is an additional bonus question at the end. Attempt it only if you have enough time.
- Give concise but adequate reasoning. You may use any statement from class or textbook without proof, but you must clearly state what you are using.
- At the end, there are some blank pages for scratch work. You may detach them.

Name: \_\_\_\_

Question	Points	Score
1	10	
2	10	
3	10	
4	10	
5	10	
Total:	50	

1. (a) (4 points) State the definition of a normal subgroup.

**Solution:** A subgroup  $H \subset G$  is called a *normal subgroup* if  $gHg^{-1} = H$  for all  $g \in G$ . Equivalently, a subgroup  $H \subset G$  is called a *normal subgroup* if gH = Hg for all  $g \in G$ .

(b) (3 points) Give an example of a normal subgroup of  $S_4$  other than  $\{e\}$  or  $S_4$ . Explain why your example is a normal subgroup.

**Solution:** Consider the alternating group  $A_4$  consisting of permutations in  $S_4$  with sign +1. Then  $A_4$  is a normal subgroup of  $S_4$  because it is the kernel of the homomorphism sgn :  $S_4 \rightarrow \{\pm 1\}$ . Also, the set {id, (12)(34), (14)(23), (13)(24)} is a normal subgroup of  $S_4$ , being the kernel of a homomorphism  $S_4 \rightarrow S_3$ .

(c) (3 points) Give an example of a subgroup of  $S_4$  that is not a normal subgroup. Explain why your example is not a normal subgroup.

**Solution:** Consider the two element subgroup  $H = {id, (12)}$ . Taking g = (13), we get  $g(12)g^{-1} = (23) \notin H$ . So H is not a normal subgroup.

2. (10 points) Let *G* be the subgroup of  $GL_2(\mathbf{R})$  defined by

$$G = \left\{ \begin{pmatrix} a & b \\ 0 & c \end{pmatrix} \mid a, b, c \in \mathbf{R}, \ ac \neq 0 \right\}.$$

Let  $H \subset G$  be the subgroup defined by a = c = 1. Prove that H is a normal subgroup of G and identify G/H.

**Solution:** Define a function 
$$\phi \colon G \to \mathbf{R}^{\times} \times \mathbf{R}^{\times}$$
 by

$$\phi\begin{pmatrix}a&b\\0&c\end{pmatrix}=(a,c).$$

Since the matrix entries *a* and *c* can be any nonzero real numbers,  $\phi$  is surjective. Let us check that  $\phi$  is a homomorphism. Let

$$M_1 = \begin{pmatrix} a_1 & b_1 \\ 0 & c_1 \end{pmatrix}$$
, and  $M_2 = \begin{pmatrix} a_2 & b_2 \\ 0 & c_2 \end{pmatrix}$ .

Then

$$M_1 M_2 = \begin{pmatrix} a_1 a_2 & a_1 b_2 + b_1 c_2 \\ 0 & c_1 c_2 \end{pmatrix}.$$

Therefore, we get

$$\phi(M_1M_2) = (a_1a_2, c_1c_2) = \phi(M_1)\phi(M_2).$$

Hence  $\phi$  is a homomorphism.

Also, 
$$\phi \begin{pmatrix} a & b \\ 0 & c \end{pmatrix} = (1, 1)$$
 if and only if  $a = c = 1$ . So, ker  $\phi = H$ .

Since the kernel of a homomorphism is a normal subgroup, we deduce that H is a normal subgroup of G.

By the first isomorphism theorem, we get

$$G/H = G/\ker\phi \cong \operatorname{im}\phi = \mathbf{R}^{\times} \times \mathbf{R}^{\times}$$

3. (10 points) Let *G* and *H* be finite groups whose orders are relatively prime (that is, gcd(|G|, |H|) = 1). Show that the only homomorphism  $\phi: G \to H$  is the trivial homomorphism:  $\phi(g) = e$  for all  $g \in G$ .

**Solution:** Let  $\phi$ :  $G \to H$  be a homomorphism. Then im  $\phi$  is a subgroup of H. By Lagrange's theorem,  $| \text{ im } \phi |$  divides |H|.

By the first isomorphism theorem, we have

 $G / \ker \phi \cong \operatorname{im} \phi$ .

In particular,  $|G| = |\ker \phi| |\operatorname{im} \phi|$ . So,  $|\operatorname{im} \phi|$  also divides |G|. Since gcd(|G|, |H|) = 1, and  $|\operatorname{im} \phi|$  divides both |G| and |H|, we conclude that  $|\operatorname{im} \phi| = 1$ . Since  $e \in \operatorname{im} \phi$ , we must have  $\operatorname{im} \phi = \{e\}$ . Therefore  $\phi(g) = e$  for all  $g \in G$ . 4. Let *G* be the group of isometries of the infinite pattern



(a) (5 points) Find the point group of *G*.

**Solution:** Recall that the point group  $\overline{G}$  of *G* is the image of *G* under the homomorphism

 $t_a A \mapsto A$ 

from the group of all isometries to the group  $O_2$  of isometries fixing the origin. Observe that *G* contains a reflection, namely the reflection through the vertical line through any crest or trough. Therefore  $\overline{G}$  contains the reflection in the *Y*-axis.

Note that *G* contains a rotation by  $\pi$  (about the midpoint between a crest and a trough). Hence  $\overline{G}$  contains the rotation by  $\pi$  about the origin.

It is clear that *G* cannot contain a rotation by a (positive) angle smaller than  $\pi$ . From what we proved in class,  $\overline{G}$  is generated by the reflection in the *Y*-axis and rotation by  $\pi$ . This group is  $D_2$ , given by

$$\overline{G} = D_2 = \{ \mathrm{id}, r_x, r_y, \rho_\pi \},\$$

where  $r_x$  is the rotation in the *x*-axis,  $r_y$  is the rotation in the *Y*-axis, and  $\rho_{\pi}$  the rotation by  $\pi$  about the origin.

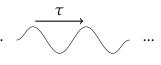
We can also see directly that  $\overline{G}$  contains the reflection in the *X*-axis by observing that *G* contains a glide along the *X*-axis.

Alternatively, we can get  $\overline{G}$  without using the above statement from class as follows. Suppose  $t_aA$  is an isometry of the pattern, where  $A \in O_2$ . Note that  $t_aA$  must send the X-axis to the X-axis. Since  $t_a$  sends a line to a parallel line, A must send the X-axis to a horizontal line. But A preserves the origin. So A must send the X-axis to itself. By orthogonality, A must send the Y-axis to the Y-axis to the Y-axis to the Y-axis to the orthogonal and preserves the two axes, it can only be one of

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}.$$

Now it is easy to check that all four possibilities are present (they come from the identity, a vertical reflection, a horizontal glide, and a rotation by  $\pi$  of the original pattern). Thus,

$$\overline{G} = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \right\}.$$



(b) (5 points) Let  $\tau$  be the translation by one wave-length. Find the number of subgroups of *G* containing  $\tau$ .

**Solution:** Any subgroup of *G* containing  $\tau$  must contain the group  $\langle \tau \rangle$  generated by  $\tau$ . By the definition of the point group  $\overline{G}$ , we have a surjective homomorphism

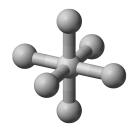
 $\phi: G \to \overline{G},$ 

whose kernel consists of the translations in *G*. But the translations in *G* are precisely the elements of  $\langle \tau \rangle$ . So we get

$$\overline{G} \cong G / \ker \phi = G / \langle \tau \rangle.$$

By the correspondence theorem for subgroups, the subgroups of *G* containing  $\langle \tau \rangle$  are in bijection with the subgroups of  $\overline{G}$ . But  $\overline{G}$  is isomorphic to the Klein four group, which has 5 subgroups: {id}, {id,  $r_x$ }, {id,  $r_y$ }, {id,  $\rho_{\pi}$ }, and {id,  $r_x$ ,  $r_y$ ,  $\rho_{\pi}$ }. Hence there are five subgroups of *G* containing  $\tau$ .

5. Let *G* be the group of orientation preserving isometries of a molecule of  $SF_6$  (sulfur hexafluoride). In coordinates, the central *S* atom is (0,0,0) and the six *F* atoms are  $(\pm 1,0,0)$ ,  $(0,\pm 1,0)$  and  $(0,0,\pm 1)$ .



(a) (5 points) Find the order of *G*.

**Solution:** Consider the action of *G* on the set of *F* atoms. All *F* atoms form one orbit. The stabilizer of an *F* atom contains four elements, namely the four rotations about the line joining that atom to *S* by angles 0,  $\pi/2$ ,  $\pi$  and  $3\pi/2$ . Remember that since we are only considering orientation preserving isometries, we must not count reflections.

By the orbit-stabilizer formula, we get

$$|G| = |O_F||G_F| = 6 \cdot 4 = 24$$

(b) (5 points) Show that there is a surjective homomorphism  $G \rightarrow S_3$ .

**Solution:** Let  $S = \{X, Y, Z\}$  be the set of the three coordinate axes. See that any isometry in *G* must take an axis to another axis. We thus get an action of *G* on *S*. Since *S* contains three elements, such an action gives a homomorphism

$$\phi \colon G \to S_3.$$

We now check that  $\phi$  is surjective. Consider the element  $g \in G$  which is the rotation by  $\pi/2$  about the positive *Z*-axis. Then  $\phi(g)$  fixes the *Z* axis, but switches the *X* and *Y* axes. In other words,  $\phi(g) = (XY)$ . Similarly, by taking *h* which is the rotation by  $\pi/2$  about the positive *Y* axis, we get  $\phi(h) = (XZ)$ . Therefore, both (XY) and (XZ) are in im  $\phi$ . Since any permutation of *X*, *Y*, *Z* can be written as a product of (XY) and (XZ), and im  $\phi$  is closed under products, we get im  $\phi = S_3$ . That is,  $\phi$  is surjective.

(c) (3 points (bonus)) Identify G.

## **Solution:** $G \cong S_4$ .

To see why, we first find a homomorphism  $G \rightarrow S_4$ . Such a homomorphism is equivalent to an action of *G* on a set with four elements. What set-of-four can we see in the picture? We have 8 octants, given by the 8 possible sign patterns of *X*, *Y*, and *Z*, namely (+, +, +), (+, +, -), etc, and we see that *G* must act on the set of octants. But 8 is too many—we want 4.

Now we see that if an isometry sends an octant O to an octant O', then it must send the octant opposite to O to the octant opposite to O' (the opposite octant is obtained by switching all three signs). We can thus pair the 8 octants into 4 pairs of opposite octants. Setting

$$S = \{$$
Pairs of opposite octants $\},\$ 

we get an action of *G* on *S*, and thus a homomorphism

$$\phi \colon G \to S_4.$$

Since both sides have the same number of elements, either surjectivity or injectivity of  $\phi$  implies that it is an isomorphism. I'll leave it to you to check this.

Scratch Work

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